

The following material is intended to provide additional insights and examples of using the Euler-Lagrange method.

1. Excerpt from "Robot Modeling and Control," by Spong, Hutchinson, Vidyasagar, Wiley, 2006.
 - a. Short derivation of Euler Lagrange equations and several robotic arm examples.
2. Excerpt from "Dynamics of Physical Systems," by Cannon, McGraw-Hill, 1967.
 - a. Short overview with several simple examples.
3. Excerpt from "Engineering Dynamics," by Ginsberg, Cambridge 2008.
 - a. Detailed derivation of Euler Lagrange equations with numerous examples.
4. Excerpt from "Dynamic Systems: Modeling and Analysis," by Vu and Esfandiari, McGraw-Hill 1997.
 - a. Slow, gentle introduction to mechanical systems.

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