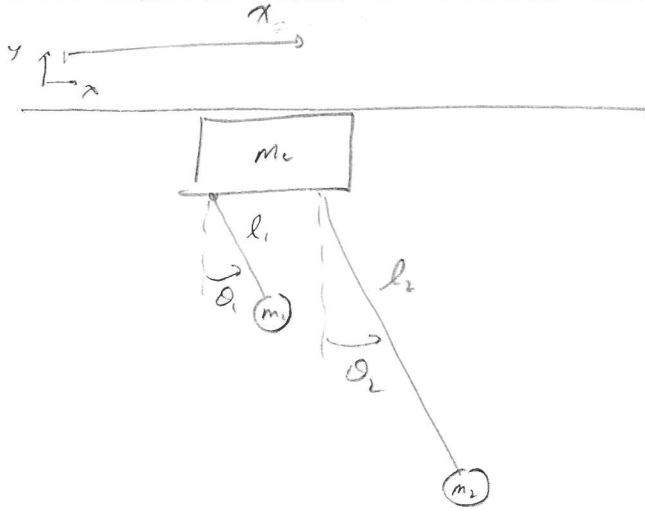


VI.1



position of cart $P_c = \begin{pmatrix} x \\ 0 \\ 0 \end{pmatrix}$

position of m_1 $P_1 = \begin{pmatrix} x + \text{offset} + l_1 \sin \theta_1 \\ \text{offset} - l_1 \cos \theta_1 \\ 0 \end{pmatrix}$

position of m_2 $P_2 = \begin{pmatrix} x + \text{offset} + l_2 \sin \theta_2 \\ \text{offset} - l_2 \cos \theta_2 \\ 0 \end{pmatrix}$

\therefore velocities are

$$v_c = \begin{pmatrix} \dot{x} \\ 0 \\ 0 \end{pmatrix}, \quad v_1 = \begin{pmatrix} \dot{x} + \dot{\theta}_1 l_1 \cos \theta_1 \\ \dot{\theta}_1 l_1 \sin \theta_1 \\ 0 \end{pmatrix}, \quad v_2 = \begin{pmatrix} \dot{x} + \dot{\theta}_2 l_2 \cos \theta_2 \\ \dot{\theta}_2 l_2 \sin \theta_2 \\ 0 \end{pmatrix}$$

\therefore The kinetic energy is

$$K = \frac{1}{2} m_c v_c^T v_c + \frac{1}{2} m_1 v_1^T v_1 + \frac{1}{2} m_2 v_2^T v_2$$

$$= \frac{1}{2} m_c \dot{x}^2 + \frac{1}{2} m_1 [(\dot{x} + \dot{\theta}_1 l_1 \cos \theta_1)^2 + (\dot{\theta}_1 l_1 \sin \theta_1)^2]$$

$$+ \frac{1}{2} m_2 [(\dot{x} + \dot{\theta}_2 l_2 \cos \theta_2)^2 + (\dot{\theta}_2 l_2 \sin \theta_2)^2]$$

$$= \frac{1}{2} m_c \dot{x}^2 + \frac{1}{2} m_1 [\dot{x}^2 + 2 \dot{\theta}_1 \dot{x} l_1 \cos \theta_1 + \dot{\theta}_1^2 l_1^2 \cos^2 \theta_1 + \dot{\theta}_1^2 l_1^2 \sin^2 \theta_1]$$

$$+ \frac{1}{2} m_2 [\dot{x}^2 + 2 \dot{\theta}_2 \dot{x} l_2 \cos \theta_2 + \dot{\theta}_2^2 l_2^2 \cos^2 \theta_2 + \dot{\theta}_2^2 l_2^2 \sin^2 \theta_2]$$

$$\therefore K = \frac{1}{2} (m_c + m_1 + m_2) \dot{x}^2 + \frac{1}{2} m_1 l_1^2 \dot{\theta}_1^2 + \frac{1}{2} m_2 l_2^2 \dot{\theta}_2^2 \\ + m_1 l_1 \dot{\theta}_1 \dot{x} \cos \theta_1 + m_2 l_2 \dot{\theta}_2 \dot{x} \cos \theta_2$$